

Motion in $\vec{E} + \vec{B}$ fields

① Motion in constant, uniform \vec{B} ($\vec{E} = 0$)

$$\frac{d\vec{p}}{dt} = q(\vec{E} + \frac{\vec{v}}{c} \times \vec{B}) \quad \frac{dU}{dt} = q\vec{v} \cdot \vec{E}$$

here $\vec{E} = 0$, $U = \text{const} \Rightarrow \gamma = \text{const}$

Recall $\vec{P} = \gamma m \vec{v}$

so $\frac{d\vec{v}}{dt} = \vec{v} \times \frac{q}{\gamma m c} \vec{B} \equiv \vec{v} \times \vec{\omega}_B$

if \vec{B} is along z direction

$$\omega_B = \frac{qB}{\gamma mc}$$

gyration
or
precession
frequency

$$\frac{dv_x}{dt} = v_y \omega_B \quad \frac{dv_y}{dt} = -v_x \omega_B \quad \frac{dv_z}{dt} = 0$$

W, II be convenient to have coordinate free form

$$\vec{v}(t) = v_{||} \hat{\vec{e}}_3 + w_B a (\hat{\vec{e}}_1 - i \hat{\vec{e}}_2) e^{-i w_B t}$$

$\hat{\vec{e}}_3$ along \vec{B} $\hat{\vec{e}}_1, \hat{\vec{e}}_2$ orthogonal unit vectors to \vec{B}

we really mean $\vec{v}(t) = \text{Re} \{ \text{above expression} \}$

$$\vec{v}(t) = v_{||} \hat{\vec{e}}_3 + w_B a (\cos w_B t \hat{\vec{e}}_1 - \sin w_B t \hat{\vec{e}}_2)$$

for RH system $\hat{\vec{e}}_1 \times \hat{\vec{e}}_2 = \hat{\vec{e}}_3$

$$\vec{x}(t) = \vec{x}_0 + v_{||} t \hat{\vec{e}}_3 + i a (\hat{\vec{e}}_1 - i \hat{\vec{e}}_2) e^{-i w_B t}$$

I.e. $\vec{x}(t) = \vec{x}_0 + v_{||} t \hat{\vec{e}}_3 + a \sin w_B t \hat{\vec{e}}_1 + a \cos w_B t \hat{\vec{e}}_2$

$$a = \text{gyration radius} = \frac{v_{\perp}}{\omega_B} = \frac{\gamma m v_{\perp} c}{q B} = \frac{c p_{\perp}}{q B}$$

Numerically

$$\frac{p_{\perp}}{\text{MeV}/c} = \frac{3.00 \times 10^{-4}}{\text{Gauss}} B \frac{a}{\text{cm}} \quad \text{for } |q| = e$$

in units $R \approx 3 \times 10^{-6}$ cm \approx about 10^{-6} ...

Suppose $|\vec{E}| < |\vec{B}|$. find frame in which $\vec{E} = 0$

a) choose \vec{u} = vel. of K' rel to K $\vec{\beta} = \vec{u}/c$

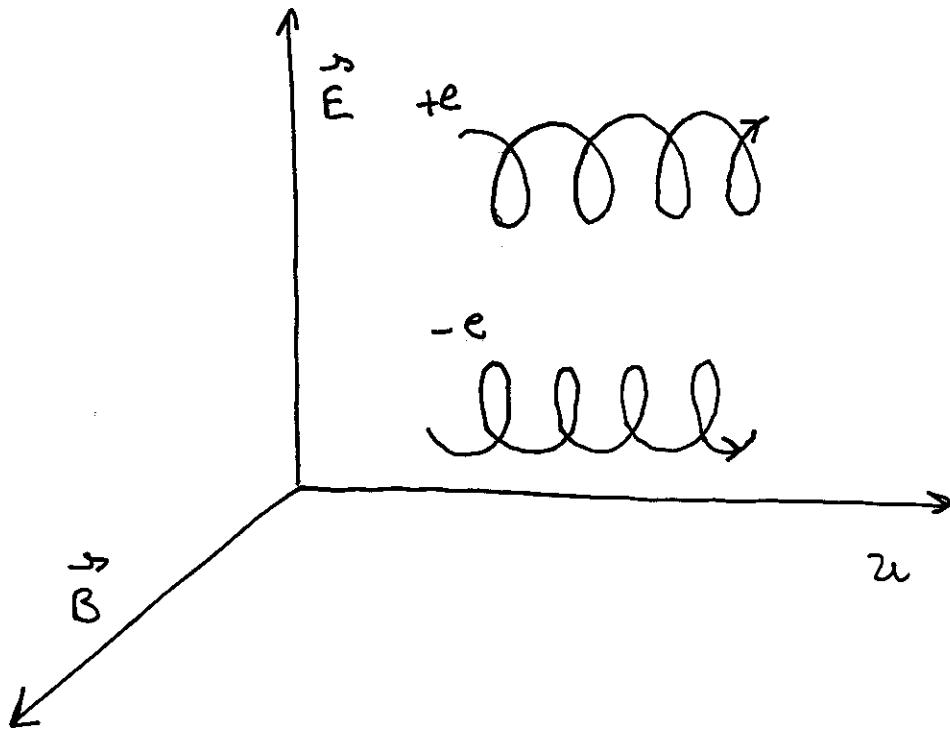
b) $\vec{u}, \vec{E}, \vec{B}$ mutually perpendicular

c) $\vec{\beta} \cdot \vec{E} = 0$ want $\vec{E} + \vec{\beta} \times \vec{B} = 0$



$$\text{so } \vec{B}' = \frac{1}{\gamma} \vec{B} = \left(1 - \frac{E^2}{B^2}\right)^{1/2} \vec{B}$$

$$\vec{B} = \frac{E}{B} \hat{\vec{B}} \quad \gamma = \left(1 - \frac{E^2}{B^2}\right)^{-1/2}$$



Both +e + -e
drift in same
direction. & in
plane containing
 \vec{B} and \vec{E}

Case $|\vec{E}| > |\vec{B}|$ - transform to frame in
which $\vec{B} = 0 \dots$

Note $\vec{E} \cdot \vec{B}$ and $E^2 - B^2$ are Lorentz invariants

So if $\vec{E} \cdot \vec{B} = 0$ ($\vec{E} \perp \vec{B}$) + $|E| < |B|$

we can find a frame in which \vec{E} vanishes

If $\vec{E} + \vec{B}$ not \perp , this wont be possible.

③ Non-uniform Static fields

Assume distance over which fields change is large compared to gyration radius of particle.

Then we have spiralling along field lines

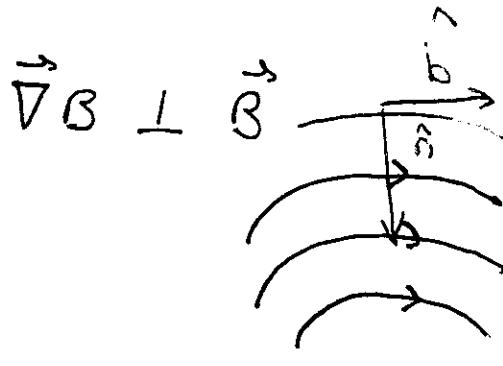
Gyration radius is set by local field strength

Center of gyration drifts slowly

Slow variations in gyration rate

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 particle
 $\underline{\text{not moving}}$
 along direction of
 \vec{B} !

Consider case where



e.g. field of wire

$\vec{B} = B(r) \hat{\phi}$ so gradient is in $\hat{\phi}$ direction for $\hat{\phi}$ field.

Use Taylor expansion to describe fields.

(first guess what happens to particle not moving along field lines)

$$\vec{B}(\vec{x}) = \vec{B}(\vec{x}_0) + (\vec{x} - \vec{x}_0) \cdot \vec{\nabla} \vec{B}(\vec{x}_0)$$

$$\text{set } \vec{x}_0 = 0, \text{ define } \vec{B}(\vec{x}_0) = \vec{B}_0$$

$$\vec{B} = B(\xi) \hat{b} \quad \xi \text{ coordinate along } \hat{n} \text{-direction of gradient}$$

$$\vec{x} \cdot \hat{n} = \xi$$

$$\vec{B}(\vec{x}) = \vec{B}_0 + (\vec{x} \cdot \hat{n}) \left(\frac{\partial B}{\partial \xi} \right)_0 \hat{b} = \vec{B}_0 \left(1 + (\hat{n} \cdot \vec{x}) \frac{1}{B_0} \left(\frac{\partial B}{\partial \xi} \right)_0 \right)$$

$$\vec{\omega}_B(\vec{x}) = \frac{e}{mc} \vec{B}(\vec{x}) = \vec{\omega}_0 \left(1 + \frac{1}{B_0} \left(\frac{\partial B}{\partial z} \right)_0 \hat{n} \cdot \vec{x} \right)$$

Now $\frac{d\vec{v}_\perp}{dt} = \vec{v}_\perp \times \vec{\omega}_B$ assume no motion along field lines

$$\text{write } \vec{v}_\perp = \vec{v}_0 + \vec{v}_i$$

$$\frac{d}{dt} (\vec{v}_0 + \vec{v}_i) = (\vec{v}_0 + \vec{v}_i) \times \vec{\omega}_0 \left(1 + \frac{1}{B_0} \left(\frac{\partial B}{\partial z} \right)_0 \hat{n} \cdot \vec{x} \right)$$

Recall $\vec{v}_o = \omega_o a (\hat{\epsilon}_1 - i \hat{\epsilon}_2) e^{-i\omega_o t}$

$$\vec{x}_o = v_{||} t \hat{\epsilon}_3 + i a (\hat{\epsilon}_1 - i \hat{\epsilon}_2) e^{-i\omega_o t} \quad \bar{x} = 0$$

$\rightarrow \quad \wedge$

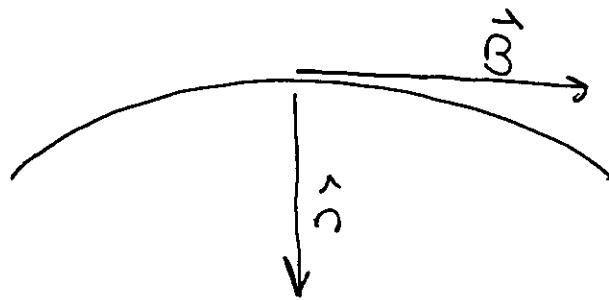
center of
gyration radius

$$\omega_o \times \epsilon_1 = \omega_o \epsilon_2$$

gives $\vec{v}_o = -\vec{\omega}_o \times \vec{x}_o$

$$\frac{d\vec{v}_1}{dt} = \left[\vec{v}_1 - \frac{1}{B_o} \left(\frac{\partial B}{\partial S} \right)_o \vec{\omega}_o \times \vec{x}_o (\hat{n} \cdot \vec{x}_o) \right] \times \vec{\omega}_o$$

Quick and dirty



Particle orbits in plane containing \hat{n} + \perp to \vec{B}
 $\hat{\epsilon}$, out of page

$$\vec{x}_o = a(\sin\omega_B t \hat{\epsilon}_i + \cos\omega_B t \hat{n})$$

$$\begin{aligned}\langle \vec{x}_o (\hat{n} \cdot \vec{x}_o) \rangle &= a^2 \langle \sin\omega_B t \epsilon_0 \sin\omega_B t \hat{\epsilon}_i + \cos^2\omega_B t \hat{n} \rangle \\ &= \frac{a^2}{2} \hat{n}\end{aligned}$$

Gradient drift velocity is $\vec{v}_G = \frac{a^2}{2} \frac{1}{B_0} \left(\frac{\partial B}{\partial \xi} \right)_0 \vec{\omega}_B \times \hat{n}$

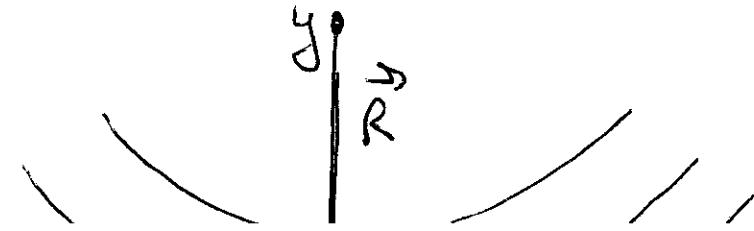
$$\vec{\omega}_B = \omega_B \frac{\vec{B}}{B}$$

$$\vec{\nabla}_{\perp} B = \hat{n} \frac{\partial B}{\partial \xi}$$

$$\frac{\vec{v}_G}{a\omega_B} = \frac{a}{2B^2} \vec{B} \times \vec{\nabla}_{\perp} B$$

positively + negatively charged particles drift in opposite directions

More generally, particle spirals along field lines



z out of page

$$\vec{r} = \rho \hat{\vec{p}} + z \hat{\vec{z}}$$

$$\vec{v} = \dot{\rho} \hat{\vec{p}} + \rho \dot{\phi} \hat{\vec{\phi}} + \dot{z} \hat{\vec{z}}$$

$$\vec{v} \times \vec{\omega}_B = -\omega_0 \frac{R}{\rho} \dot{\rho} \hat{\vec{z}} - \omega_0 \frac{R}{\rho} \dot{z} \hat{\vec{p}}$$

$$\vec{p} = (\ddot{\rho} - \omega_0^2 z) \hat{\vec{p}} + (\omega_0 \ddot{z} + \dot{\rho} \dot{z}) \hat{\vec{z}} + \ddot{z} \hat{\vec{\phi}}$$

$$① \quad \ddot{\rho} - \rho \dot{\phi}^2 = -\omega_0 \frac{R}{\rho} \dot{z}$$

$$② \quad \rho \ddot{\phi} + 2\dot{\rho} \dot{\phi} = 0$$

$$③ \quad \ddot{z} = \omega_0 \frac{R}{\rho} \dot{\rho}$$

$$④ \quad \text{conservation of ang. momentum} \quad \rho^2 \dot{\phi} = L = \text{constant}$$

$$\dot{z} = R\omega_0 \ln \rho/R + v_0 \quad v_0 \text{ integration constant}$$

$$\ddot{\rho} - \frac{L^2}{\rho^3} = -\omega_0^2 R^2 \frac{\ln \rho/R}{\rho} - \omega_0 v_0 \frac{R}{\rho}$$

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Now we assume $\omega_0 R = v_\perp$

$$\Rightarrow \begin{cases} v_0 \\ v_R = v_{\parallel} \end{cases}$$

then

$$\frac{x_{eq}}{R} = \frac{L^2}{\omega_0^2 R^4} - \frac{v_0}{\omega_0 R}$$

$$= \frac{v_{\parallel}^2}{\omega_0^2 R^2} - \frac{v_0}{\omega_0 R}$$

$$= \frac{\langle x \rangle}{R}$$

$$\langle \dot{z} \rangle = v_0 + \omega_0 \langle x \rangle = \frac{v_{\parallel}^2}{\omega_0 R}$$

$$= v_c \quad \text{curvature drift}$$

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